

Contents

Introduction Introduction to Models and Functions 1

- 0.1 Models in Life Sciences 1**
 - Types of Dynamical Systems 4
- 0.2 Variables, Parameters, and Functions 7**
 - Describing Measurements with Variables, Parameters, and Graphs 7
 - Describing Relations between Measurements with Functions 10
 - Catalogue of Important Functions 16
 - Exercises 19
- 0.3 Working with Functions 21**
 - Inverse Functions 26
 - Creating New Functions 33
 - Transformations of Graphs 34
 - Exercises 39

Chapter 1 Modelling Using Elementary Functions 43

- 1.1 Elementary Models 43**
 - Proportional Relations 43
 - Linear Functions 46
 - Power Functions 52
 - Exercises 58
- 1.2 Exponential and Logarithmic Functions; Exponential Models 60**
 - Exponential Functions 60
 - Logarithmic Functions 63
 - Basic Exponential Model 66
 - Exercises 74
- 1.3 Trigonometric and Inverse Trigonometric Functions 76**
 - Angles and Trigonometric Ratios 76
 - Trigonometric Functions 79
 - Describing Oscillations 81
 - Inverse Trigonometric Functions 85
 - Exercises 88
 - Supplementary Problems 90

Chapter 2 Discrete-Time Dynamical Systems 93

- 2.1 Introduction to Discrete-Time Dynamical Systems 93**
 - Discrete-Time Dynamical Systems and Updating Functions 93
 - Solutions 96
 - Manipulating Updating Functions 103
 - Discrete-Time Dynamical Systems: Units and Dimensions 106
 - Exercises 107

2.2 Analysis of Discrete-Time Dynamical Systems	110
Cobwebbing: A Graphical Solution Technique	111
Equilibria: Geometric Approach	113
Equilibria: Algebraic Approach	115
Exercises	119
2.3 Modelling with Discrete-Time Dynamical Systems	121
Absorption of Caffeine	122
Bacterial Population Growth in General	123
Dynamics of Alcohol Use	128
Exercises	131
2.4 A Model of Gas Exchange in the Lung	133
A Model of the Lungs	133
The Lung System in General	136
Lung Dynamics with Absorption	140
Exercises	142
2.5 Nonlinear Dynamics Model of Selection	144
A Model of Selection	144
The Discrete-Time Dynamical System and Equilibria	148
Stable and Unstable Equilibria	151
Exercises	152
Supplementary Problems	156
Project	158

Chapter 3 Limits, Continuity, and Derivatives

159

3.1 Investigating Change	159
The Average Rate of Change	159
Instantaneous Rate of Change	162
Limits and Derivatives	165
Exercises	166
3.2 Limit of a Function	168
Limit	168
Calculating Limits	172
Calculating Limits Algebraically—Limit Laws	174
Exercises	179
3.3 Infinite Limits and Limits at Infinity	182
Infinite Limits	182
Limits at Infinity	186
Infinite Limits at Infinity	191
Application to Absorption Functions	198
Limits of Sequences	200
Exercises	202
3.4 Continuity	204
Continuous Functions	205
Input and Output Precision	213
Hysteresis	214
Exercises	215
3.5 Derivatives and Differentiability	217
Differentiable Functions	217
Graphs and Derivatives	221
Exercises	226
Supplementary Problems	229
Project	231

Chapter 4 Working with Derivatives**233**

- 4.1 Derivatives of Powers, Sums, and Polynomials 233**
 - Derivative of Constant and Power Functions 233
 - The Sum (Difference) Rule for Derivatives 237
 - Derivatives of Polynomials 237
 - Exercises 241
- 4.2 Derivatives of Products and Quotients 242**
 - The Product Rule 242
 - The Quotient Rule 246
 - Exercises 249
- 4.3 Derivatives of Exponential and Logarithmic Functions 251**
 - The Exponential Function 251
 - The Natural Logarithm 255
 - Exercises 257
- 4.4 The Chain Rule 258**
 - The Derivative of a Composite Function 258
 - Implicit Differentiation 263
 - Exercises 268
- 4.5 Derivatives of Trigonometric and Inverse Trigonometric Functions 269**
 - Derivatives of Sine and Cosine 269
 - Other Trigonometric Functions 274
 - Derivation of the Key Limits 275
 - Derivatives of Inverse Trigonometric Functions 277
 - Exercises 279
- 4.6 The Second Derivative, Curvature, Concavity, and Acceleration 281**
 - The Second Derivative 281
 - Using the Second Derivative for Graphing 285
 - Applications 287
 - Acceleration 289
 - Exercises 290
- 4.7 Approximating Functions with Polynomials 293**
 - The Tangent and Secant Lines 293
 - Quadratic Approximation 297
 - Taylor Polynomials 301
 - Exercises 303
 - Supplementary Problems 305
 - Project 306

Chapter 5 Applications of Derivatives**307**

- 5.1 Extreme Values of a Function 307**
 - Minima and Maxima 307
 - Absolute Extreme Values 316
 - Maximizing the Rate of Food Intake 320
 - Exercises 324
- 5.2 Reasoning About Functions: Continuity and Differentiability 327**
 - Continuous Functions: The Intermediate Value Theorem 327
 - Maximization: The Extreme Value Theorem 331
 - Rolle's Theorem and the Mean Value Theorem 332
 - Continuity and Differentiability 335
 - Exercises 337

5.3	Leading Behaviour and L'Hôpital's Rule	339
	Leading Behaviour of Functions at Infinity	339
	Leading Behaviour of Functions at 0	343
	The Method of Matched Leading Behaviours	345
	L'Hôpital's Rule	347
	Exercises	354
5.4	Newton's Method	356
	Solving Equations	356
	Newton's Method	357
	Exercises	364
5.5	Stability of Discrete-Time Dynamical Systems	365
	Motivation	366
	Stability and the Slope of the Updating Function	369
	Evaluating Stability with the Derivative	371
	Exercises	376
5.6	The Logistic Dynamical System and More Complex Dynamics	378
	The Logistic Dynamical System	378
	Qualitative Dynamical Systems	381
	Analysis of the Logistic Dynamical System	386
	Exercises	390
5.7	Case Study: Panting and Deep Breathing	392
	Breathing at Different Rates	392
	Deep Breathing	393
	Panting	394
	Intermediate Optimum	395
	Exercises	396
	Supplementary Problems	397
	Projects	399

Chapter 6 Integrals and Applications

401

6.1	Differential Equations	401
	Differential Equations: Examples and Terminology	404
	Graphical Solution of Pure-Time Differential Equations	408
	Euler's Method for Solving for Differential Equations	410
	Exercises	416
6.2	Antiderivatives	418
	Antiderivatives	418
	Rules for Antiderivatives	421
	Solving Simple Differential Equations	425
	Exercises	429
6.3	Definite Integral and Area	431
	Area	431
	Sigma Notation	437
	Area and Definite Integral	437
	The Definite Integral	441
	Properties of Integrals	446
	Exercises	451
6.4	Definite and Indefinite Integrals	453
	The Fundamental Theorem of Calculus:	
	Computing Definite Integrals with Indefinite Integrals	453
	The Integral Function and the Proof of the Fundamental Theorem of Calculus	461
	Exercises	467

6.5 Techniques of Integration: Substitution and Integration by Parts 469

A Useful Shortcut 469

The Chain Rule and Integration by Substitution 471

Integration by Parts 478

Exercises 485

6.6 Applications 487

Integrals and Areas 487

Integrals and Averages 493

Integrals and Mass 495

Exercises 496

6.7 Improper Integrals 498

Infinite Limits of Integration 499

Improper Integrals: Examples 500

Infinite Integrands 506

Exercises 510

Supplementary Problems 511

Projects 512

Chapter 7 Differential Equations**515****7.1 Basic Models with Differential Equations 515**

Review of Autonomous Differential Equations 515

Exercises 524

7.2 Equilibria and Display of Autonomous Differential Equations 528

Equilibria 528

Graphical Display of Autonomous Differential Equations 530

Exercises 532

7.3 Stability of Equilibria 534

Recognizing Stable and Unstable Equilibria 534

Applications of the Stability Theorem 536

A Model of a Disease 538

Exercises 541

7.4 Separable Differential Equations 543

Separation of Variables 543

Exercises 550

7.5 Systems of Differential Equations; Predator-Prey Model 552

Predator-Prey Dynamics 553

Dynamics of Competition 554

Newton's Law of Cooling 555

Applying Euler's Method to Systems of Autonomous Differential Equations 557

Exercises 560

7.6 The Phase Plane 562

Equilibria and Nullclines: Predator-Prey Equations 562

Equilibria and Nullclines: Competition Equations 565

Equilibria and Nullclines: Newton's Law of Cooling 566

Exercises 567

7.7 Solutions in the Phase Plane 569

Euler's Method in the Phase Plane 570

Direction Arrows: Predator-Prey Equations 573

Direction Arrows: Competition Equations 576

Direction Arrows: Newton's Law of Cooling 578

Exercises 579

7.8 The Dynamics of a Neuron 581

- A Mathematician's View of a Neuron 581
- The Mathematics of Sodium Channels 582
- The Mathematics of Sodium Channel Blocking 583
- The Fitzhugh-Nagumo Equations 584
- Weak Channel Blocking Mechanism 585
- The Effects of Constant Applied Current 586
- Exercises 586
- Supplementary Problems 587
- Projects 589

Answers 591**Index I-1**