

## Robotica

*Robotica* aims to be an outlet for publication of original papers of the highest quality in the field of Robotics and closely related areas. This includes: novel robotic mechanism and actuator design; robot kinematics, dynamics and control; computer vision; sensor fusion; teleoperation and haptic interfaces; robot motion planning; and artificial intelligence. In addition, papers that apply techniques from Robotics to other fields are also welcome. Examples include dynamics and control models applied to biological systems, the description of implementations of robots in factories, service and agricultural settings, and general mechatronic design. Works may be theoretical, computational or experimental, or some combination. Both short papers (rapid communications), and longer archival papers are welcome. Proposals for special issues on topics of current interest are welcome, and can be submitted via email to the editor.

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- P.W. Anderson, "More is different" *Science* 177, 393-399 (1972);  
C.V. Negoita, *Fuzzy Systems* (Abacus Press. Tunbridge Wells, UK, 1980).

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